

QISKIT Global Summer School 2020 Notes

Sandesh Katakam

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1 Lecture 1: Qubits and Quantum States, Quantum Circuits, Measurements - Part 1

1.1 From bits to qubits: Dirac Notation, Measurements, Bloch Sphere

- Classical states for computation are either "0" or "1"
- In QM, a state can be in superposition, i.e., simultaneously in "0" and "1"
 - Superposition's allow to perform calculations on many gates at the same time.
 - Quantum algorithms with exponential speed-up.
 - **BUT:** once we measure the superpositions state, it will collapse to one of its states.
 - **(we can only get one "answer" and not all answer to all states in superposition)**
 - It is not that easy to design quantum algorithms, but we use interference effects.
 - **("wrong answers" cancel each other out, while the "right answer" remains)**

• Dirac Notation:

- Used to describe quantum states: Let

$$a, b \in \mathbb{C}^2$$

$$* \text{ ket } : |a\rangle = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix}$$

$$* \text{ bra } : \langle b| = |b\rangle^t = \begin{pmatrix} b_1 \\ b_2 \end{pmatrix}^t = (b_1^* \quad b_2^*)$$

$$* \text{ bra - ket } : \langle b|a\rangle = a_1 \times b_1^* + a_2 \times b_2^* = \langle a|b\rangle^*$$

* **ket – bra** : $|a\rangle\langle b| = \begin{pmatrix} a_1 b_1^* & a_1 b_2^* \\ a_2 b_1^* & a_2 b_2^* \end{pmatrix}$

- We define the states:

$$|0\rangle := \begin{pmatrix} 0 & 1 \end{pmatrix}$$

which are orthogonal:

$$\langle 0|1\rangle = 1 \cdot 0 + 0 \cdot 1$$

- All quantum states are normalized, i.e.,

$$\langle \psi | \psi \rangle = 1$$

e.g.

$$|\psi\rangle = \frac{1}{\sqrt{2}} \cdot (|0\rangle + |1\rangle) = \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix}$$

• Measurements:

- We choose orthogonal bases to describe and measure quantum states (projective measurement)
- During a measurement onto the basis $\{|0\rangle, |1\rangle\}$, the state will collapse into either state $|0\rangle$ or $|1\rangle$ as those are the eigenstates of σ_z , we call this a Z-measurement
- There are infinitely many different bases, but other common ones are:
 $\{|+\rangle := \frac{1}{\sqrt{2}}, |-\rangle := \frac{1}{\sqrt{2}}\}$ and $\{|+i\rangle := \frac{1}{\sqrt{2}}, |-i\rangle := \frac{1}{\sqrt{2}}\}$
corresponding to the eigenstates of σ_x and σ_y .
- **Born Rule:** The probability that a state $|\psi\rangle$ collapses during a projective measurement onto the basis $\{|x\rangle, |x\rangle\}$ to the state $|x\rangle$ is given by:

$$P(x) = |\langle x | \psi \rangle|^2$$

$$\sum_i P(x_i) = 1$$

* Examples:

- $|\psi\rangle = \frac{1}{\sqrt{3}}(|0\rangle + \sqrt{2}|1\rangle)$ is measured in the basis $\{|0\rangle, |1\rangle\}$:

$$P(0) = \left| \langle 0 | \frac{1}{\sqrt{3}} (|0\rangle + \sqrt{2} \cdot |1\rangle) \right|^2 = \left| \frac{1}{\sqrt{3}} \cdot \langle 0|0\rangle + \frac{\sqrt{2}}{\sqrt{3}} \cdot \langle 0|1\rangle \right|^2 = \frac{1}{3} ; P(1) = \frac{2}{3}$$

- $|\psi\rangle = \frac{1}{\sqrt{2}}(|0\rangle - |1\rangle)$ is measured in the basis $\{|+\rangle, |-\rangle\}$:

$$\begin{aligned} P(+) &= |\langle + | \psi \rangle|^2 = \left| \frac{1}{\sqrt{2}} \cdot (\langle 0| + \langle 1|) + \frac{1}{\sqrt{2}} \cdot (|0\rangle - |1\rangle) \right|^2 \\ &= \frac{1}{4} \left| \langle 0|0\rangle - \langle 0|1\rangle + \langle 1|0\rangle - \langle 1|1\rangle \right|^2 = 0 \end{aligned}$$

expected as $\langle + | \psi \rangle = \langle + | - \rangle = 0$

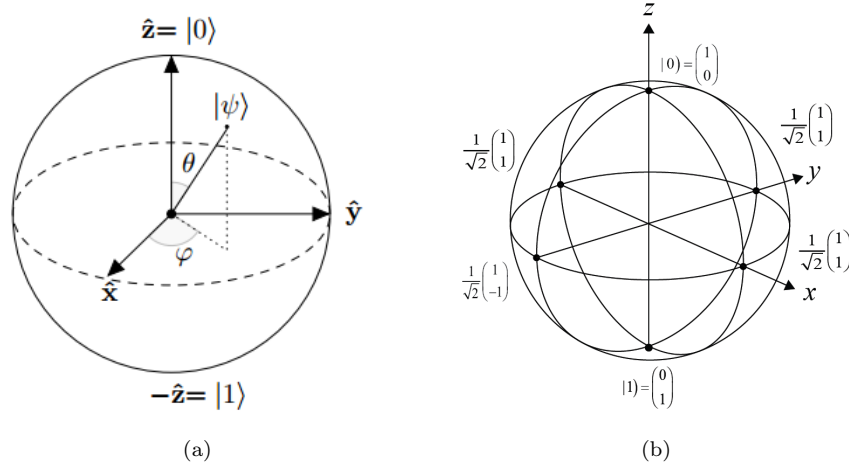


Figure 1: Bloch Sphere

• Bloch Sphere:

- We can write any normalized(pure) state as $|\psi\rangle = \cos \frac{\theta}{2} \cdot |0\rangle + e^{i\phi} \sin \frac{\theta}{2} \cdot |1\rangle$, where $\phi \in [0, 2\pi]$ describes the relative phase and $\theta \in [0, \pi]$ determines the probability to measure $|0\rangle$ / $|1\rangle$:

$$P(|0\rangle) = \cos^2 \frac{\theta}{2}, \quad P(|1\rangle) = \sin^2 \frac{\theta}{2}$$

- * All normalized pure states can be illustrated on the surface of a sphere with radius \vec{r} , which we call the **Bloch Sphere**
- * The coordinates of such a state are given by the **Bloch Vector**:

$$\vec{r} = \begin{pmatrix} \sin \theta \cos \phi \\ \sin \theta \sin \phi \\ \cos \theta \end{pmatrix}$$

– Examples:

$$|0\rangle : \theta = 0, \phi \text{ is arbitrary} \rightarrow \vec{r} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$|1\rangle : \theta = \pi, \phi \text{ is arbitrary} \rightarrow \vec{r} = \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix}$$

$$|+\rangle : \theta = \frac{\pi}{2}, \phi = 0 \rightarrow \vec{r} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

$$|-\rangle : \theta = \frac{\pi}{2}, \phi = \pi \rightarrow \vec{r} = \begin{pmatrix} -1 \\ 0 \\ 0 \end{pmatrix}$$

$$|+i\rangle : \theta = \frac{\pi}{2}, \phi = \frac{\pi}{2} \rightarrow \vec{r} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

$$|-i\rangle : \theta = \frac{\pi}{2}, \phi = \frac{3\pi}{2} \rightarrow \vec{r} = \begin{pmatrix} 0 \\ -1 \\ 0 \end{pmatrix}$$

- **Be Careful:** On the Bloch sphere, angles are twice as big as in Hilbert Space, e.g. $|0\rangle$ $|1\rangle$ are orthogonal, but on the Bloch sphere their angle is 180deg. For a general state $|\psi\rangle = \cos \frac{\theta}{2} |0\rangle + \dots$ Here θ is the angle on the Bloch Sphere, while $\frac{\theta}{2}$ is the actual angle in the Hilbert Space!
- Z-measurement corresponds to a projection onto the z-axis and analogously for X and Y!

1.2 Quantum Circuits : basic single-qubit and two-qubit gate, multi-partite quantum states

1.3 Entanglement: Bell states, Teleportation, Q-shpere

Examples include:

- the **double slit experiment** (done with light by Thomas Young in 1801, and with electrons by Tonomura in 1986)
- the photoelectric effect (analyzed by Einstein in 1905 — in fact his Nobel-winning work)
- the “quantum Venn diagram” puzzle, involving the overlaps of three polarizing filters
- the stability of the hydrogen atom (i.e., the fact that the electron doesn’t lose energy and spiral inward toward the proton).

Remark 1. *How now, brown cow?*

Definition 1. *The Feynman kernel is given by*

$$K(x_b, t_b; x_a, t_a) = \int_{x(t_a)=x_a}^{x(t_b)=x_b} e^{(i/\hbar)S[x(t)]} \mathcal{D}x(t).$$

1.4 Mon, Sept 9: Review of Newtonian Mechanics

- A *Newtonian trajectory* $\mathbf{x}(t)$ ($t \in \mathbb{R}$) is given by solutions of the second order ODE

$$m \ddot{\mathbf{x}}(t) = \mathbf{F}(\mathbf{x}(t)),$$

where $m > 0$ is a basic parameter associated with a given Newtonian particle, called its *mass*.

- The force field $\mathbf{F}(\mathbf{x})$ — which we take to be static (i.e., not intrinsically dependent on time) for simplicity — is said to be *conservative* if there is a *potential function* $V(\mathbf{x})$ such that

$$\mathbf{F}(\mathbf{x}) = -\nabla V(\mathbf{x}).$$

Here, ‘ ∇ ’ denotes the *gradient operator*,

$$\nabla V = \left(\frac{\partial V}{\partial x}, \frac{\partial V}{\partial y}, \frac{\partial V}{\partial z} \right).$$

- For a conservative force field, we can find a *conserved quantity* along the Newtonian trajectories, namely the *total mechanical energy*.

$$E = H(\mathbf{x}, \mathbf{p}) := \frac{1}{2m} \mathbf{p}^2 + V(\mathbf{x}).$$

Here, $\mathbf{p}^2 := \mathbf{p} \cdot \mathbf{p} = \|\mathbf{p}\|^2$, and $\mathbf{p} := m\mathbf{v} := m\dot{\mathbf{x}}$ is the *momentum*.

1.5 Tue, Sept 10: Alternative Formulations of Newtonian Mechanics

- The **Hamiltonian formulation**:

$$\dot{\mathbf{x}} = \frac{\partial H}{\partial \mathbf{p}}, \quad \dot{\mathbf{p}} = -\frac{\partial H}{\partial \mathbf{x}}.$$

- The **Lagrangian formulation**:

$$\delta S[\mathbf{x}(t)] = 0,$$

where the *action* on the time interval $[t_a, t_b]$ is given by

$$S[\mathbf{x}(t)] := \int_{t_a}^{t_b} \left[\frac{m}{2} \dot{\mathbf{x}}(t)^2 - V(\mathbf{x}(t)) \right] dt.$$

- Etc.